

Parallel Assemblies Plot

a visualization tool to explore categorical and quantitative data: application to digital mobility outcomes

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From Newcastle. For the world.

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Mobilise-D Project

The Mobilise-D project aim at developing a system to evaluate people's gait based on **digital technologies** to monitor the following heath condition:

- > Multiple Sclerosis
- > Chronic Obtrusive Pulmonary Disease
- > Parkinson's Disease
- > Chronic Heart Failure
- > Periprosthetic Femoral Fracture

More than **300 professionals** from **34 participating universities**, **hospitals**, and **industry**, representing **11 countries**, with the necessary technical, clinical, and regulatory expertise are working together over a five-year period.



Effect on mobility

| Multiple Sclerosis (MS) | Chronic Obstructive Pulmonary Disease (COPD) | Parkinson's Disease (PD) | Chronic Heart Failure (CHF) | Periprosthetic Femoral Fracture (PFF) |
|---|---|--|---|---|
| limit walking endurance | increase duration between steps | > gait slowness > increased step | can reduce walking capacity | affect gait and balance functions |
| cause weakness, poor balance, numbness, or spasticity | increase step duration variability | variability> poor posturalcontrol | | |
| | | | | |







Evaluating mobility in clinical context

CURRENTLY

Medical questionnaires

- Imprecise: Health status X ranked on small scale (e.g. 0 to 5)
- X Subjective: Depend on the context (different clinicians, relative to the previous patient, ...)

| 2.12 W | ALKING A | ND BALANCE |
|----------|-------------|---|
| Over the | e past weel | k, have you usua |
| 0: 1 | Normal: | Not at all (no p |
| 1: 3 | Slight: | I am slightly slo |
| 2: | Mild: | l occasionally u another persor |
| 3: | Moderate: | l usually use a falling. Howev∉ person. |
| 4: 3 | Severe: | l usually use th falling. |

In-lab evaluation

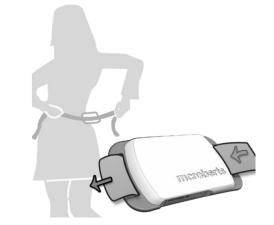
- X Not convenient: require patient to come to the lab for a long period of time
- X Not ecologically valid: Snap shot rather than continuous change



WITH ACCELEROMETRY SENSORS

Real-life mobility tracking

- > Precise: provides quantitative metrics on how people walk
- > Objective: rely on accelerometry recording
- Convenient: easy to equip
- > Ecologically valid: can be wear at all time



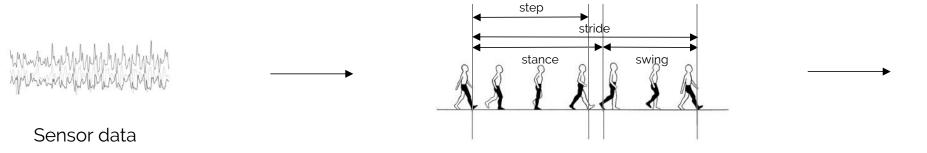
Project overview

TVS – Technical Validation Study

from sensor data to mobility outcomes

CVS - Clinical Validation Study

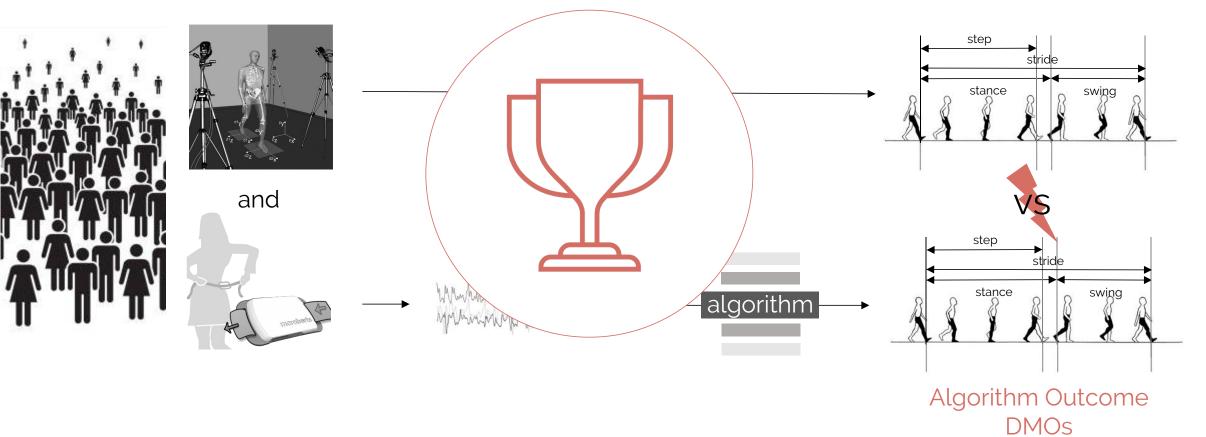
from mobility outcomes to health status



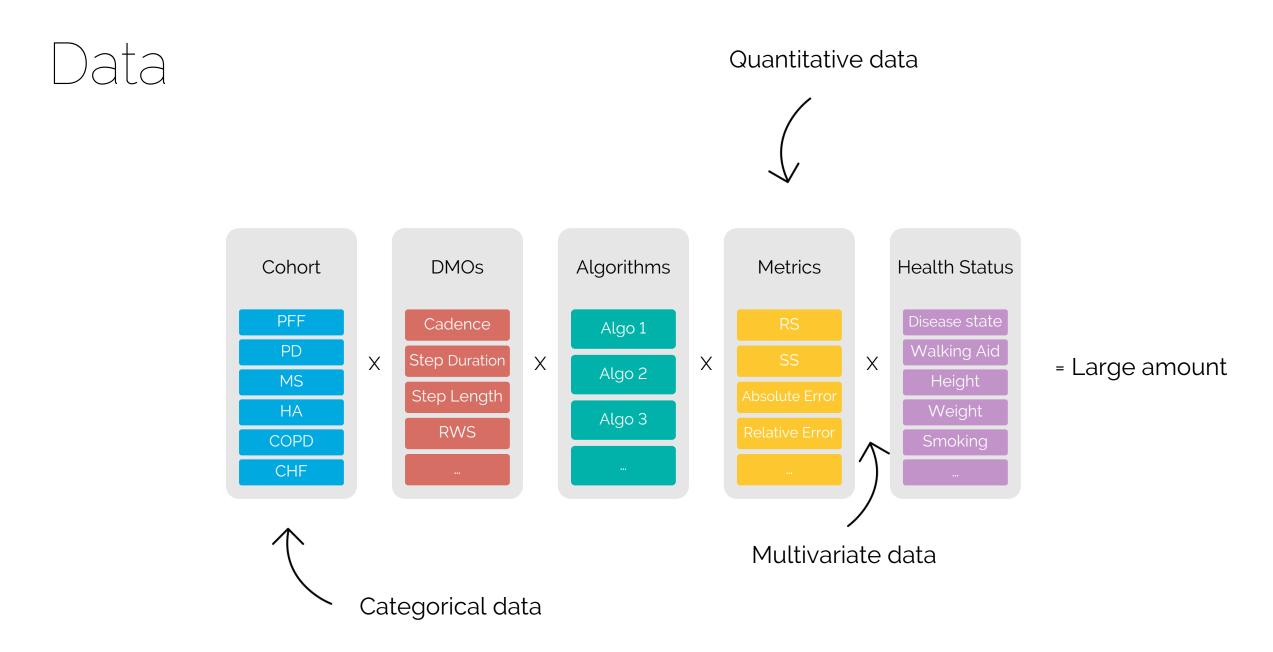
Digital Mobility Outcomes (DMO)

Health status

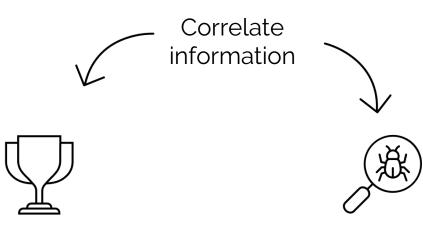
TVS Methodology



Reference DMOs









Identify and understand outliers



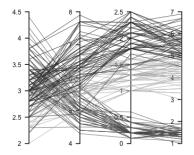


/ Involve expertise

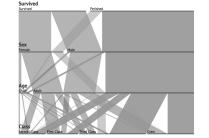


Visualization

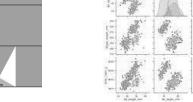
Existing work



Parallel Coordinates

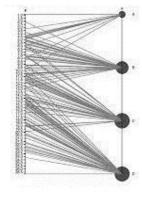


Parallel Sets



Scatterplots matrix

3D Scatterplot



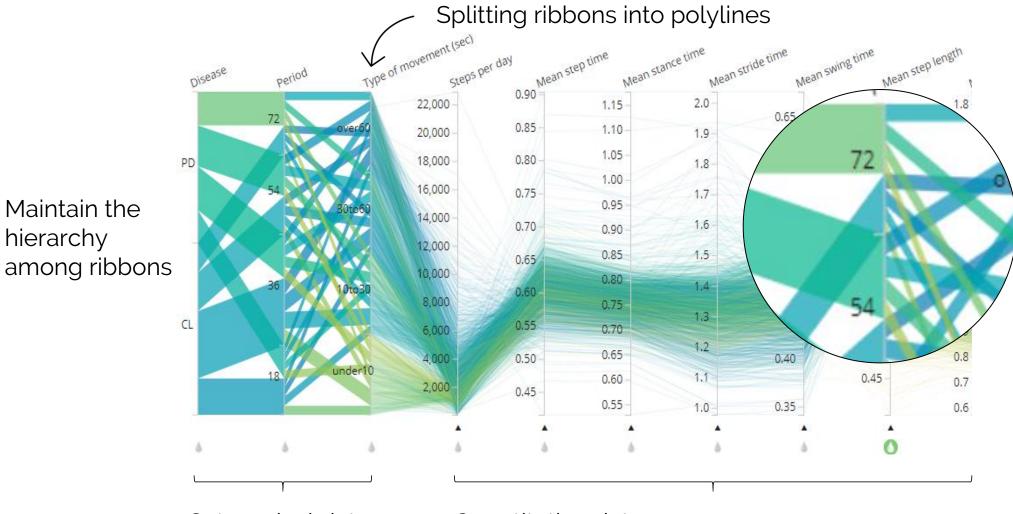
Parallel Bubble

Limits

No categorial and quantitative data combined

- or Loss of frequency information
- or Loss of precision
- or Limited correlation

Our solution for heterogeneous data



Color ribbons according to the average values of the category

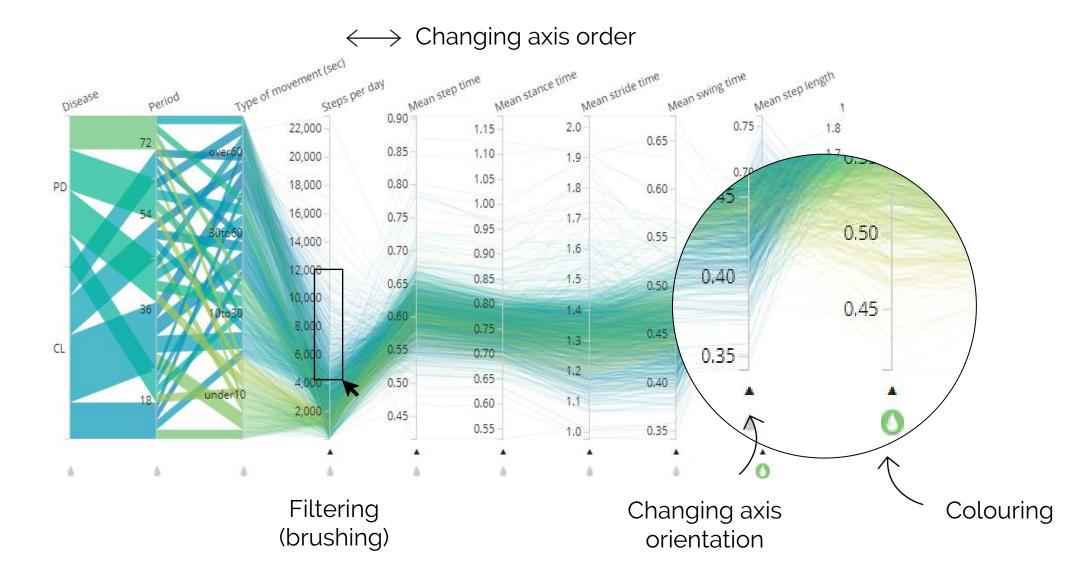
Categorical data

Maintain the

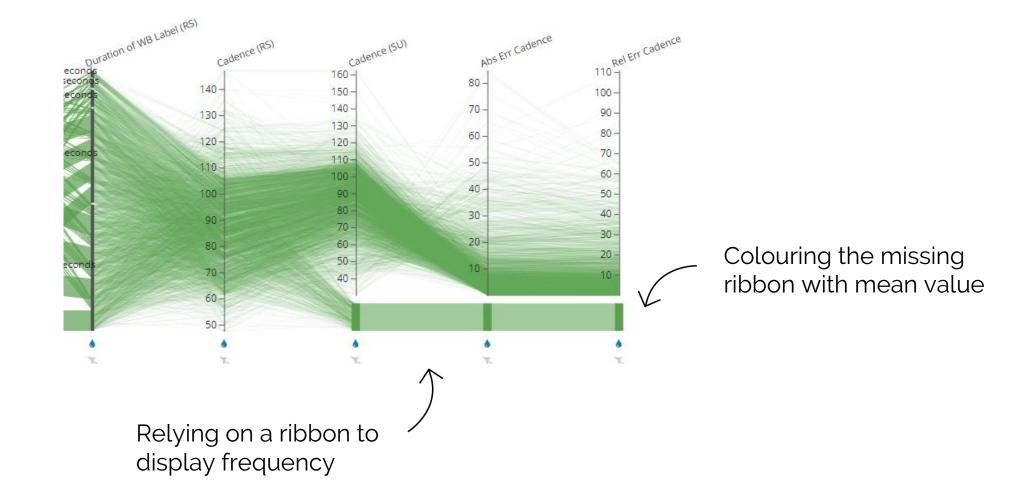
hierarchy

Quantitative data

Parallel axis features



Missing values



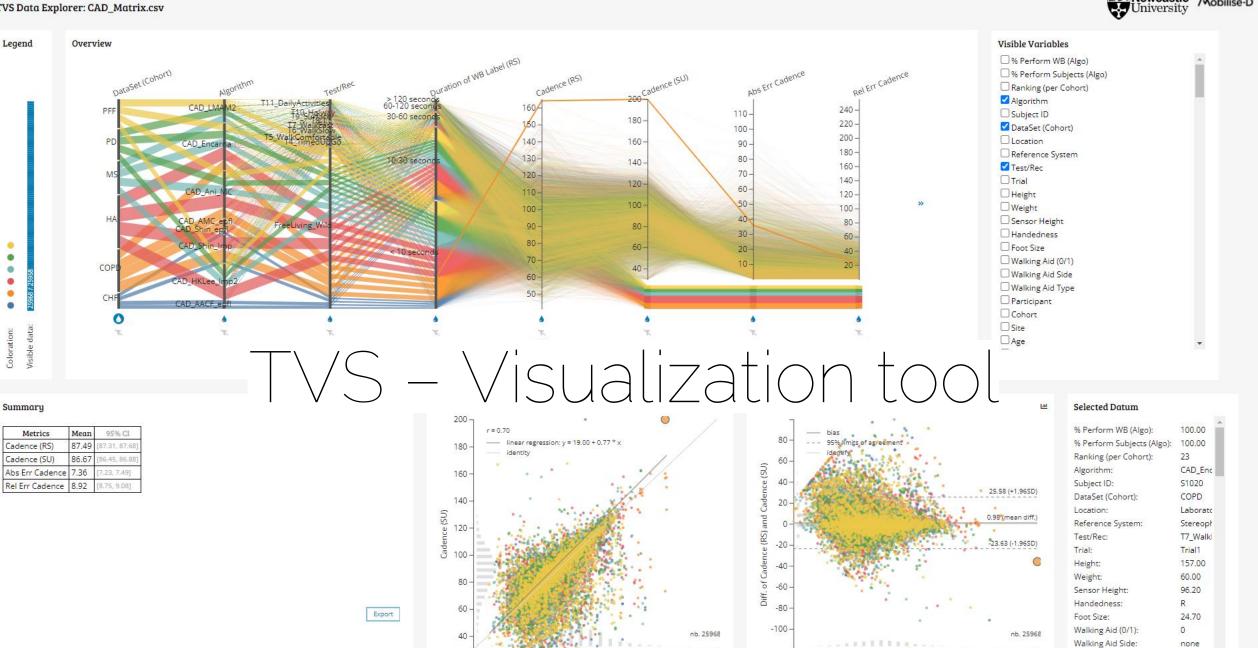
TVS Data Explorer: CAD_Matrix.csv

0

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0

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80

S

100

120

Cadence (RS)

140

160

180 20 40

60

80

100

120

Mean of Cadence (RS) and Cadence (SU)

140

160

180

CAD_Enc Laborate Stereoph T7_Walk

none

1000

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Walking Aid Type:

D



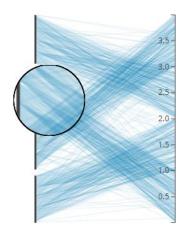
Qualitative study Are experts able to better perform their tasks?



- -> identification of pipeline errors
- -> identification of outliers
- -> identification of correlation

Quantitative evaluation

Is the junction between ribbons and polyline extend the correlation properties of existing work?



- -> some identifications are faster
- -> some identifications are more accurate
- -> it allows to correlate more dimensions

Additional Information

Technology

- > JavaScript d3.js
- > Two data access versions
 - CSV loading
 - Link to data base with Flask

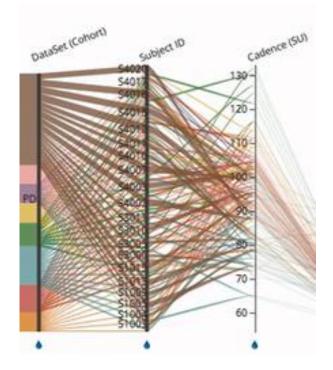
Fully data-dynamic

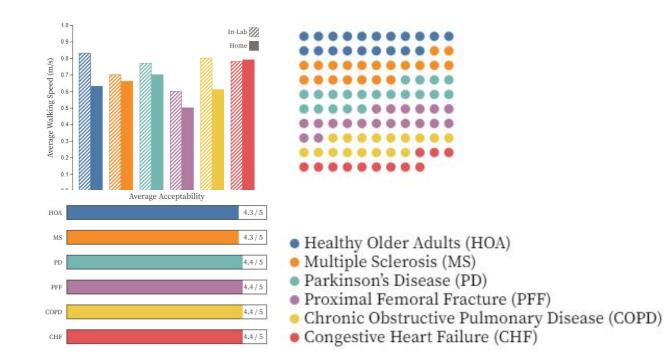
- > Any data can be loaded as long as categorical and quantitative data are identified
- > Currently working on
 - community behaviour analysis results
 - network flow analysis

Not available on git hub yet

- > will be available at the end of the project
- > some features are still under publication process
- > contact me if you want to access older version: alma.cantu@newcastle.ac.uk

Future work



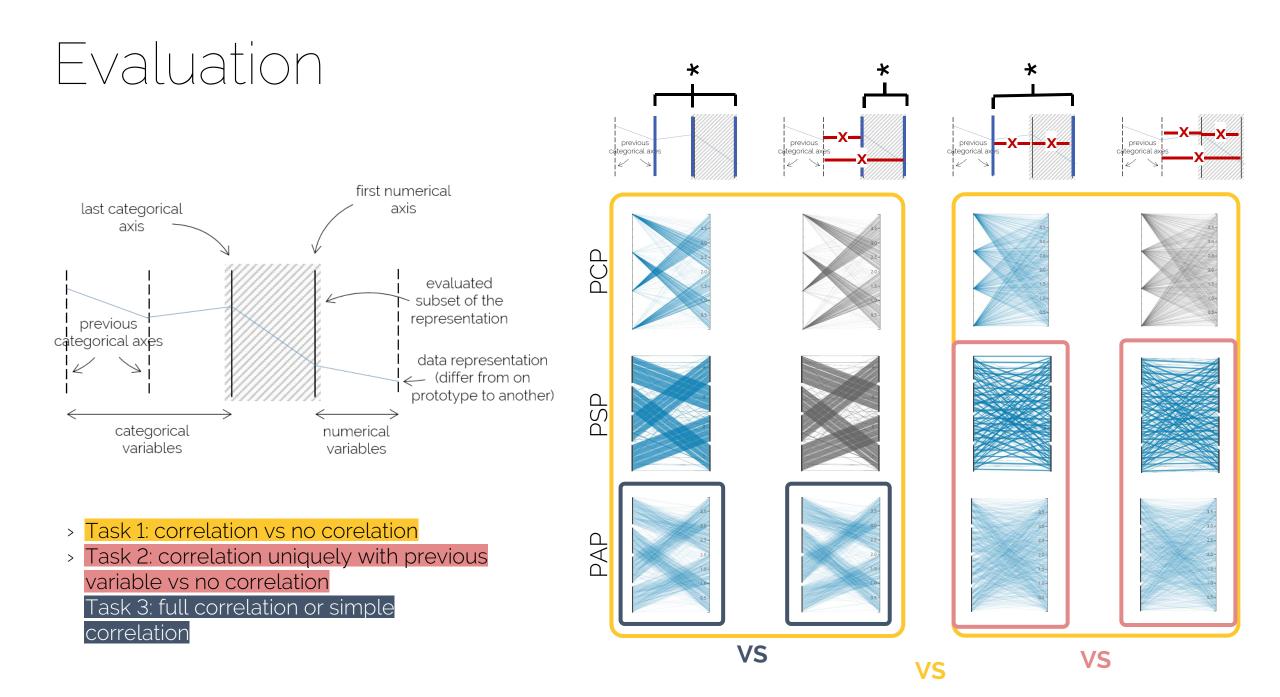


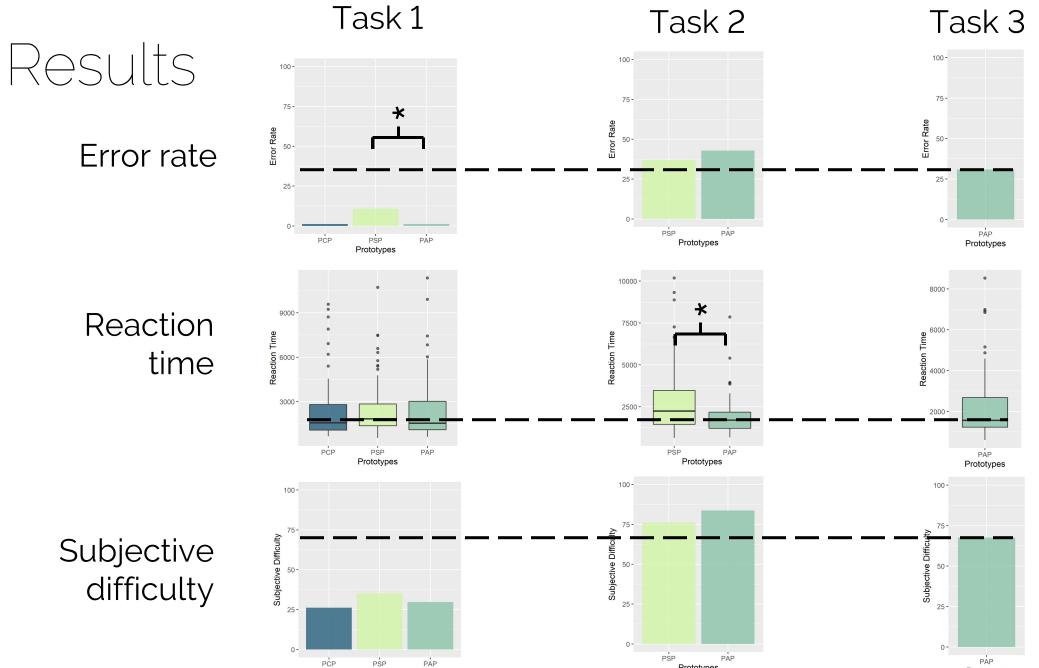
Aggregation technique

Visualization for patients

Thank you for your attention

Learn more on research.ncl.ac.uk/nova/projects/



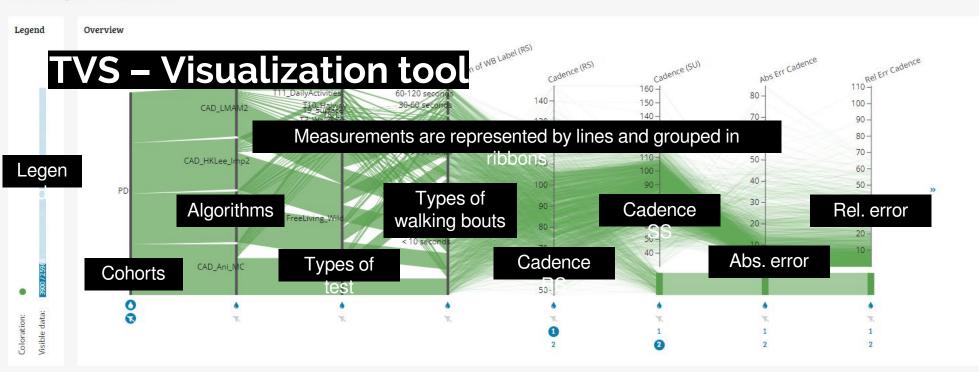


Prototypes

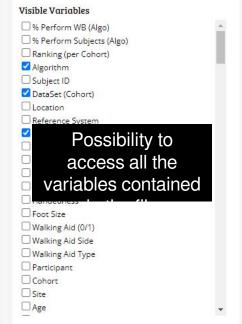
PSP

Prototypes

PAP Prototypes



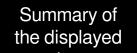
Export

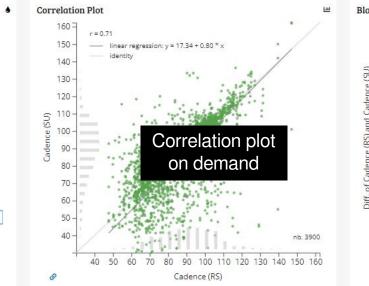


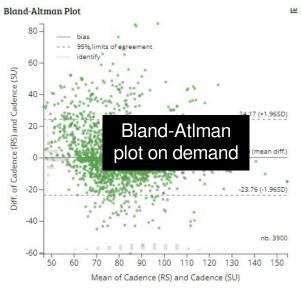
Newcastle Mobilise-D

Summary

| Metrics | Mean | 95% CI |
|-----------------|-------|----------------|
| Cadence (RS) | 87.21 | [86.74, 87,68] |
| Cadence (SU) | 87.18 | [86.62, 87.74] |
| Abs Err Cadence | 7.24 | [6.91, 7.57] |
| Rel Err Cadence | 8.87 | [8.47, 9.27] |





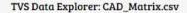


Selected Datum

| | | <u>.</u> |
|----------------------------|---------|----------|
| % Perform WB (Algo): | 100.00 | 1 |
| % Perform Subjects (Algo): | 100.00 | |
| Ranking (per Cohort): | 23 | |
| Algorithm: | CAD_Enc | |
| Subject ID: | S1020 | |
| DataSet (Cohort): | COPD | |
| | | |

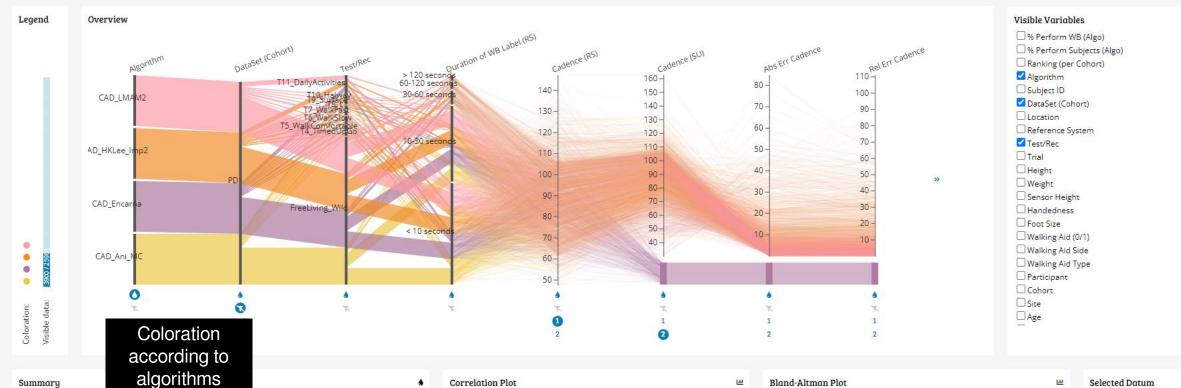
Access to detail on

| Height: | 157.00 | | |
|--------------------|--------|--|--|
| Weight: | 60.00 | | |
| Sensor Height: | 96.20 | | |
| Handedness: | R | | |
| Foot Size: | 24.70 | | |
| Walking Aid (0/1): | 0 | | |
| Walking Aid Side: | none | | |
| Walking Aid Type: | none | | |
| D | 1070 | | |



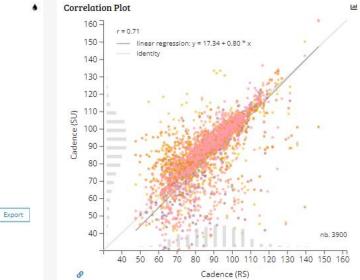


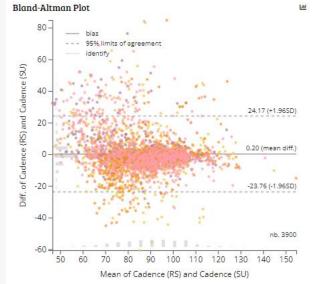
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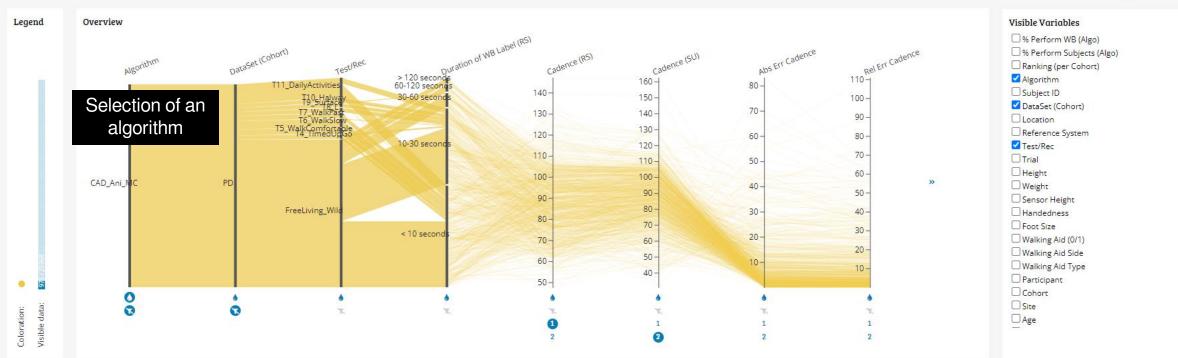
Selected Datum

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|----------------------------|----------|---|
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| Algorithm: | CAD_Enc | |
| Subject ID: | S1020 | |
| DataSet (Cohort): | COPD | |
| Location: | Laborate | |
| Reference System: | Stereoph | |
| Test/Rec: | T7_Walk | |
| Trial: | Trial1 | |
| Height: | 157.00 | |
| Weight: | 60.00 | |
| Sensor Height: | 96.20 | |
| Handedness: | R | |
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| Walking Aid (0/1): | 0 | |
| Walking Aid Side: | none | |
| Walking Aid Type: | none | _ |
| P | 1000 | * |



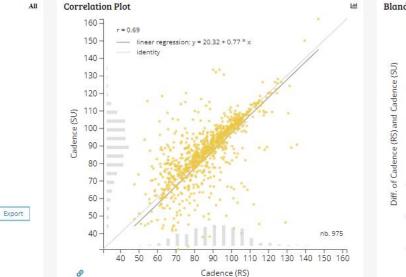


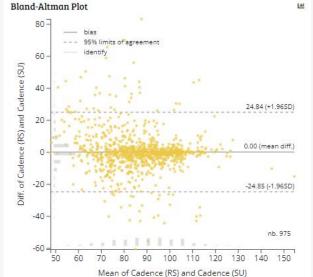
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Summary

| Per color | CAD_Ani_MC | | | |
|-----------------|------------|----------------|--|--|
| Metrics | Mean | 95% CI | | |
| Cadence (RS) | 87.21 | [86,27, 88,15] | | |
| Cadence (SU) | 87.21 | [86.16, 88.26] | | |
| Abs Err Cadence | 7.37 | [6.73, 8.02] | | |
| Rel Err Cadence | 9.11 | [8.30; 9.92] | | |

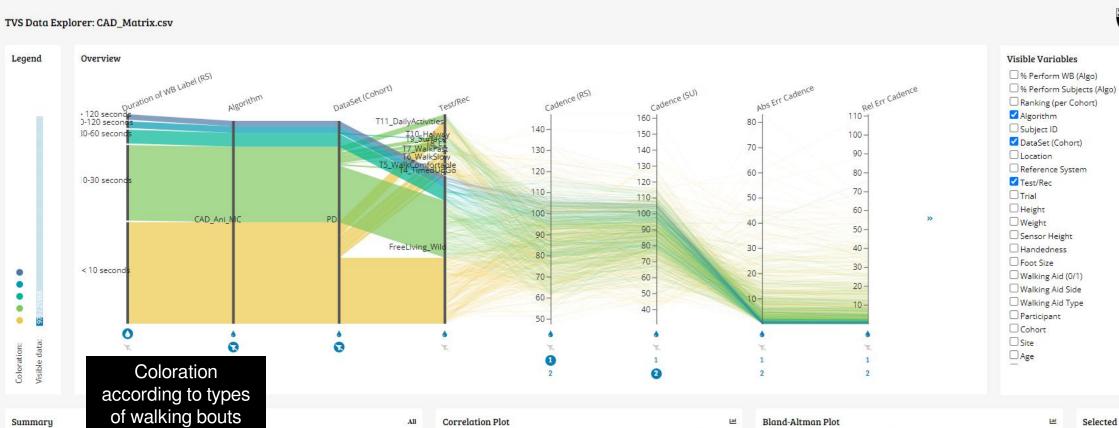




Selected Datum

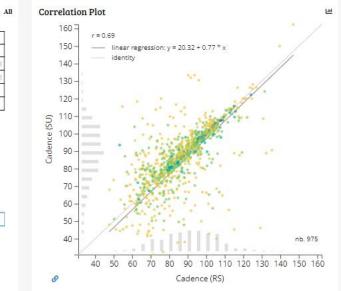
| % Perform WB (Algo): | 100.00 | Ì |
|----------------------------|----------|---|
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| Height: | 157.00 | |
| Weight: | 60.00 | |
| Sensor Height: | 96.20 | |
| Handedness: | R | |
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| Walking Aid Side: | none | |
| Walking Aid Type: | none | |
| D | 1010 | |



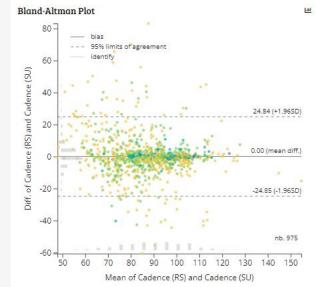


| Summary | |
|---------|--|
| | |

| Per color | < 10 seconds | | 10-30 | 10-30 seconds 30-60 | | seconds 60-12 | | 0 seconds > | | 120 seconds | |
|-----------------|--------------|----------------|-------|-----------------------|-------|----------------|-------|----------------|--------|------------------|--|
| Metrics | Mean | 95% CI | Mean | 95% CI | Mean | 95% CI | Mean | 95% CI | Mean | 95% CI | |
| Cadence (RS) | 85.54 | [84.12, 86.95] | 86.60 | [85.19, 88.00] | 92.53 | [89.29, 95.77] | 94.80 | [91.94, 97.67] | 104.27 | [101.83, 106,71] | |
| Cadence (SU) | 85.47 | [83.77, 87.17] | 86.61 | (85.19, 88,04) | 92.95 | [90.16; 95.73] | 94.82 | [91.92, 97.72] | 104.36 | [102:00, 106:73] | |
| Abs Err Cadence | 9.74 | [8.65, 10.84] | 6.05 | [5.27, 6.83] | 2.92 | [1.62, 4.22] | 0.96 | (0.55, 1.36) | 0.47 | [0.31, 0.63] | |
| Rel Err Cadence | 12.04 | [10.70, 13.37] | 7.48 | [6.48, 8.49] | 3.75 | [1:45, 6.04] | 1.00 | [0.58, 1.41] | 0.45 | [0.30, 0.59] | |



Export



Selected Datum

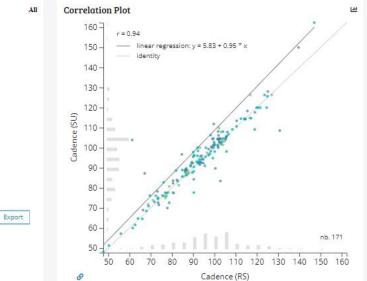
| % Perform WB (Algo): | 100.00 | |
|----------------------------|----------|---|
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| Walking Aid Side: | none | |
| Walking Aid Type: | none | |
| n | 1010 | * |

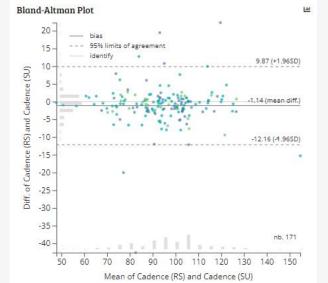
University Kobilise-D



Summary

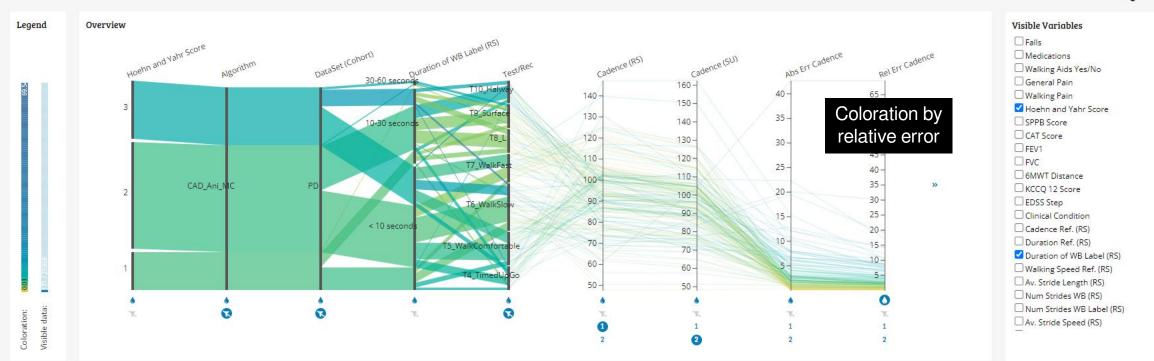
| Per color | 1 | | 2 | | 3 | |
|-----------------|-------|----------------|-------|----------------|-------|-----------------|
| Metrics | Mean | 95% CI | Mean | 95% CI | Mean | 95% CI |
| Cadence (RS) | 92.98 | [88.29, 97.66] | 93.10 | [89.41, 96,79] | 95.83 | [91,49, 100,17] |
| Cadence (SU) | 94.06 | [89:14, 98.98] | 93.88 | [90.12; 97.65] | 97.68 | [93.56, 101.79] |
| Abs Err Cadence | 2.26 | [1.48, 3.03] | 2.51 | [1.92, 3.10] | 5.13 | [3.03, 7.22] |
| Rel Err Cadence | 2.40 | [1.64, 3.16] | 2.71 | {2.12, 3.30} | 5.93 | [2.90, 8.97] |





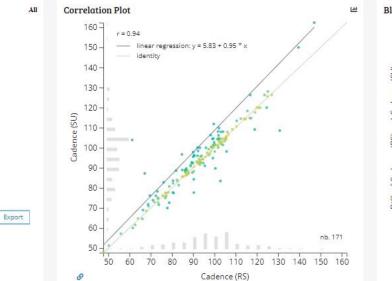
Selected Datum

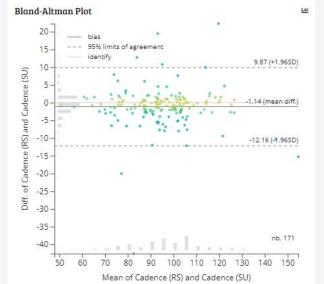
| N/ Daufana WD (Alaa) | 100.00 | * |
|----------------------------|----------|---|
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| D+: -:+ | 1070 | - |



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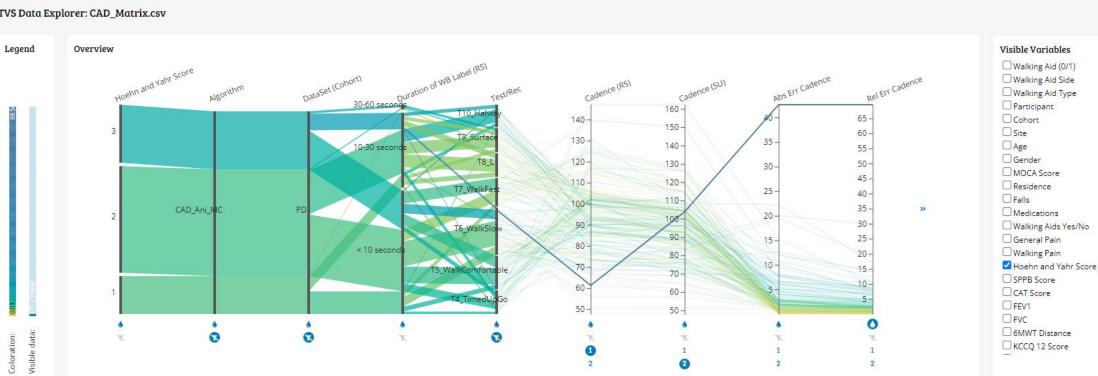




≝ Selected Datum

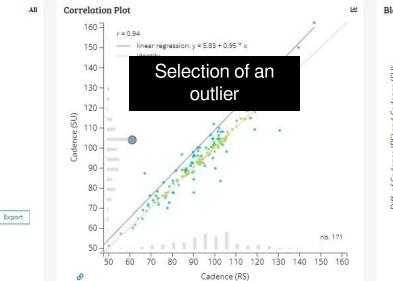
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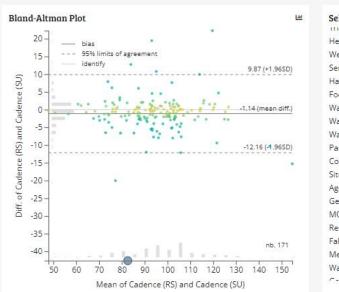




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| Rel Err Cadence | 3.58 | [2.62, 4.53] |





| Selected Datum | | |
|----------------------|-----------|---|
| ITIdi. | India | |
| Height: | 156.00 | |
| Weight: | 83.00 | |
| Sensor Height: | 98.90 | |
| Handedness: | R | |
| Foot Size: | 27.00 | |
| Walking Aid (0/1): | 1 | |
| Walking Aid Side: | Bilateral | |
| Walking Aid Type: | Rollator | |
| Participant: | 4017 | |
| Cohort: | PD | |
| Site: | CAU | |
| Age: | 70.00 | |
| Gender: | Female | |
| MOCA Score: | 20.00 | |
| Residence: | Nursing | |
| Falls: | 10.00 | |
| Medications: | Dridase, | |
| Walking Aids Yes/No: | Y | |
| C I D-: | 22.00 | * |

Mewcastle Mobilise-D